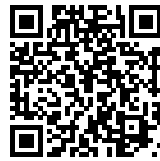


# RADIX-2 FAST FOURIER TRANSFORM

[http://www.phys.uconn.edu/~rozman/Courses/m3511\\_19s/](http://www.phys.uconn.edu/~rozman/Courses/m3511_19s/)



Last modified: January 22, 2019

## 1 Discrete Fourier transform

The *discrete*, or *finite*, *Fourier transform* (DFT) of a (complex) vector  $\mathbf{x}$  with  $N$  elements  $(x_0, x_1, \dots, x_{N-1}) = \{x_n\}$  is another vector  $\mathbf{X}$  with  $N$  elements  $(X_0, X_1, \dots, X_{N-1}) = \{X_k\}$ ,

$$X_k = \sum_{n=0}^{N-1} x_n e^{-\frac{2\pi i}{N}kn} = \sum_{n=0}^{N-1} \omega^{kn} x_n, \quad (1)$$

where  $i = \sqrt{-1}$ ,  $k = 0, 1, \dots, N-1$ , and we introduce the notation

$$\omega = e^{-\frac{2\pi i}{N}}. \quad (2)$$

The discrete Fourier transform can be expressed with matrix-vector notation:

$$\mathbf{X} = \mathbf{F}_N \mathbf{x}, \quad (3)$$

where the Fourier matrix  $\mathbf{F}$  has the elements

$$\left(\mathbf{F}_N\right)_{kn} = \omega^{kn}, \quad k, n = 0, 1, \dots, N-1. \quad (4)$$

$$F_N = \begin{pmatrix} \omega^0 & \omega^0 & \omega^0 & \dots & \omega^0 \\ \omega^0 & \omega^1 & \omega^2 & \dots & \omega^{N-1} \\ \omega^0 & \omega^2 & \omega^4 & \dots & \omega^{2(N-1)} \\ \omega^0 & \omega^3 & \omega^6 & \dots & \omega^{3(N-1)} \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ \omega^0 & \omega^{N-1} & \omega^{2(N-1)} & \dots & \omega^{(N-1)^2} \end{pmatrix}. \quad (5)$$

In matlab the DFT can be coded, for example, as shown in Listing 1.

```

1 function X = mynaivedft(x)
2 % MYNAIVEDFT - naive implementation of the discrete Fourier transform
3     np = length(x);
4     omega = exp(-2*pi*1i/np);
5     n = 0:np-1;
6     k = n';
7     F = omega.^(k*n);
8     X = F*x;
9 end

```

Listing 1: Naive MATLAB implementation of the discrete Fourier transform

Direct application of the definition Eq. (1) shown Listing 1 in requires  $N$  multiplications and  $N$  additions for each of the  $N$  components of  $\mathbf{X}$  for a total of  $2N^2$  floating-point operations. This does not include the generation of the matrix  $F$ .

## 2 Radix-2 algorithm

Radix-2 algorithm is a member of the family of so called Fast Fourier transform (FFT) algorithms. It computes separately the DFTs of the even-indexed inputs ( $x_0, x_2, \dots, x_{N-2}$ ) and of the odd-indexed inputs ( $x_1, x_3, \dots, x_{N-1}$ ), and then combines those two results to produce the DFT of the whole sequence. This idea can then be performed recursively to reduce the overall runtime from  $O(N^2)$  to  $O(N \log N)$ . Radix-2 algorithm requires that  $N$

is a power of two; since the number of sample points  $N$  can usually be chosen freely by the application, this is often not an important restriction.

To derive the algorithm, let's rearrange the DFT of  $\mathbf{x}$ , Eq. (1), into two parts: a sum over the even-numbered indices and a sum over the odd-numbered indices:

$$X_k = \sum_{m=0}^{N/2-1} x_{2m} e^{-\frac{2\pi i}{N} (2m)k} + \sum_{m=0}^{N/2-1} x_{2m+1} e^{-\frac{2\pi i}{N} (2m+1)k}. \quad (6)$$

One can factor a common multiplier  $e^{-\frac{2\pi i}{N} k}$  out of the second sum.

$$X_k = \sum_{m=0}^{N/2-1} x_{2m} e^{-\frac{2\pi i}{N} (2m)k} + e^{-\frac{2\pi i}{N} k} \sum_{m=0}^{N/2-1} x_{2m+1} e^{-\frac{2\pi i}{N} (2m)k}. \quad (7)$$

The two sums in Eq. (7) are the DFT of the even-indexed part and the DFT of odd-indexed part of  $x_n$ . Denote the DFT of the even-indexed inputs by  $E_k$  and the DFT of the odd-indexed inputs by  $O_k$  and we obtain:

$$X_k = \underbrace{\sum_{m=0}^{N/2-1} x_{2m} e^{-\frac{2\pi i}{(N/2)} mk}}_{\text{DFT of even-indexed part}} + e^{-\frac{2\pi i}{N} k} \underbrace{\sum_{m=0}^{N/2-1} x_{2m+1} e^{-\frac{2\pi i}{(N/2)} mk}}_{\text{DFT of odd-indexed part}} = E_k + e^{-\frac{2\pi i}{N} k} O_k. \quad (8)$$

As the functions of  $k$   $E_k$  and  $O_k$  are periodic with the period  $N/2$ :

$$E_{k+\frac{N}{2}} = E_k \quad (9)$$

and

$$O_{k+\frac{N}{2}} = O_k. \quad (10)$$

Therefore, we can rewrite Eq. (8) as

$$X_k = \begin{cases} E_k + e^{-\frac{2\pi i}{N} k} O_k & \text{for } 0 \leq k < N/2, \\ E_{k-N/2} + e^{-\frac{2\pi i}{N} k} O_{k-N/2} & \text{for } N/2 \leq k < N, \end{cases} \quad (11)$$

where we used the periodicity of  $O_k$  and  $E_k$  to translate the index  $k$ .

Using the following property of the *twiddle* factor  $e^{-2\pi i k/N}$ ,

$$e^{-\frac{2\pi i}{N} (k+N/2)} = e^{-\frac{2\pi i k}{N} - \pi i} = e^{-\pi i} e^{-\frac{2\pi i k}{N}} = -e^{-\frac{2\pi i k}{N}}$$

we can rewrite  $X_k$  as:

$$\begin{aligned} X_k &= E_k + e^{-\frac{2\pi i}{N}k} O_k, \\ X_{k+\frac{N}{2}} &= E_k - e^{-\frac{2\pi i}{N}k} O_k. \end{aligned}$$

This result, expressing the DFT of length  $N$  recursively in terms of two DFTs of size  $N/2$ , is the core of the radix-2 fast Fourier transform.

---

```

1  function X = myradix2dft(x)
2  % MYRADIX2DFT radix-2 discrete Fourier transform
3      np = length(x); % must be a power of two
4      if np == 1
5          X = x;
6      else
7          xe = x(1:2:end);
8          xo = x(2:2:end);
9          xe = myradix2dft(xe);
10         xo = myradix2dft(xo);
11         omega = exp(-2*pi*1i/np);
12         k = (0:(np/2-1))';
13         w = omega.^k;
14         xo = w.*xo;
15         X = [xe+xo; xe-xo];
16     end
17 end

```

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Listing 2: MATLAB implementation of radix-2 discrete Fourier transform

### 3 The number of floating point operations

The DFT of length  $N$  is expressed in terms of two DFTs of length  $N/2$ , then four DFTs of length  $N/4$ , then eight DFTs of length  $N/8$ , and so on until we reach  $N$  DFTs of length one. An DFT of length one is just the number itself. If  $N = 2^p$ , the number of steps in the recursion is  $p = \log_2 N$ . There is  $O(N)$  work at each step, independent of the step number, so the total amount of work is  $O(Np) = O(N \log_2 N)$ .

## 4 Inverse DFT

The Fourier matrix  $F_N$  has the explicit inverse:

$$\left(F_N^{-1}\right)_{kn} = \frac{1}{N} \omega^{-kn}, \quad k, n = 0, 1, \dots, N-1, \quad (12)$$

or

$$F_N^{-1} = \frac{1}{N} \begin{pmatrix} \omega^0 & \omega^0 & \omega^0 & \dots & \omega^0 \\ \omega^0 & \omega^{-1} & \omega^{-2} & \dots & \omega^{-(N-1)} \\ \omega^0 & \omega^{-2} & \omega^{-4} & \dots & \omega^{-2(N-1)} \\ \omega^0 & \omega^{-3} & \omega^{-6} & \dots & \omega^{-3(N-1)} \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ \omega^0 & \omega^{-(N-1)} & \omega^{-2(N-1)} & \dots & \omega^{-(N-1)^2} \end{pmatrix}. \quad (13)$$

Eq. (1) can be inverted as following:

$$x_k = \frac{1}{N} \sum_{n=0}^{N-1} X_n \omega^{-kn} = \frac{1}{N} \sum_{n=0}^{N-1} X_n e^{\frac{2\pi i}{N} kn}. \quad (14)$$

To prove that indeed,

$$F_N F_N^{-1} = F_N^{-1} F_N = I, \quad (15)$$

where  $I$  is the identity matrix, notice that

$$1 + \omega + \omega^2 + \omega^3 + \dots + \omega^{N-1} = 0, \quad (16)$$

since the sum on the left of Eq. (16) is an  $N$ -terms geometric progression with the start value  $\omega^0 = 1$  and the common ratio  $\omega$ . The value of the sum is

$$\frac{1 - \omega^N}{1 - \omega} = 0 \quad (17)$$

since

$$\omega^N = \left(e^{-\frac{2\pi i}{N}}\right)^N = e^{-2\pi i} = 1, \quad (18)$$

and thus the numerator in Eq. (17) is zero whereas the denominator is not.

Similarly, we can show that

$$1 + \omega^2 + \omega^4 + \omega^6 + \dots + \omega^{2(N-1)} = 0, \quad (19)$$

$$1 + \omega^3 + \omega^6 + \omega^9 + \dots + \omega^{3(N-1)} = 0, \quad (20)$$

and in general

$$1 + \omega^k + \omega^{2k} + \omega^{3k} + \dots + \omega^{(N-1)k} = 0, \quad k = 1, \dots, N-1 \text{ and } k = -N+1, \dots, -1. \quad (21)$$

However, when  $k = 0$  the sum in Eq. (21)

$$1 + \omega^k + \omega^{2k} + \omega^{3k} + \dots + \omega^{(N-1)k} = 1 + 1 + 1 + \dots + 1 = N. \quad (22)$$

Summarizing Eqs. (21), (22):

$$\sum_{l=0}^{N-1} \omega^{lk} = N \delta_{k0} = \begin{cases} 0, & k = 1, \dots, N-1 \text{ and } k = -N+1, \dots, -1 \\ N, & k = 0, \end{cases} \quad (23)$$

where  $\delta_{mn}$  is the Kronecker symbol.

Finally,

$$\left( \mathbf{F}_N \mathbf{F}_N^{-1} \right)_{kp} = \sum_{l=0}^{N-1} (\mathbf{F}_N)_{kl} (\mathbf{F}_N^{-1})_{lp} = \frac{1}{N} \sum_{l=0}^{N-1} \omega^{kl} \omega^{-lp} = \frac{1}{N} \sum_{l=0}^{N-1} \omega^{l(k-p)} = \delta_{kp}. \quad (24)$$