

Induced emf in a circular loop¹

A circular wire loop of resistance R and radius a has its center at a distance $d_0 > a$ from a long straight wire. The wire is in the plane of the loop. (See Fig. 1.) The current in the long wire is changing, $I = I(t)$. What is the current in the loop?

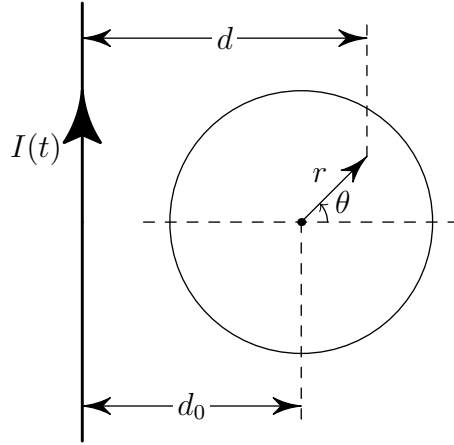


Figure 1: A long straight wire carrying current $I(t)$ and a circular wire loop whose center is distance d_0 from the wire.

The emf induced in the loop has the magnitude

$$\varepsilon = \left| \frac{d\Phi}{dt} \right| = \left| \frac{d}{dt} \int B_n dA \right|, \quad (1)$$

where Φ is the magnetic flux through the loop,

$$\Phi = \int B_n dA, \quad (2)$$

B_n is the component of the magnetic field perpendicular to the plane of the loop; the integration is over the area of the loop. The magnetic field produced by the wire at a radial distance d from the wire,

$$B_n = \frac{\mu_0 I}{2\pi d}. \quad (3)$$

At a point inside the loop,

$$d = d_0 + r \cos \theta \quad (4)$$

and

$$dA = r dr d\theta, \quad (5)$$

so that the flux through the loop is

$$\Phi = \frac{\mu_0 I}{2\pi} \int_0^{2\pi} \int_0^a \frac{r dr d\theta}{d_0 + r \cos \theta} = \frac{\mu_0 I}{2\pi} \int_0^a \phi(r) r dr. \quad (6)$$

¹The physics problem in this note is “borrowed” from: S. Lea, *Mathematics for Physicists*, Brooks Cole, 2003

The integral over θ ,

$$\phi(r) = \int_0^{2\pi} \frac{d\theta}{d_0 + r \cos \theta}. \quad (7)$$

Change the integration variable:

$$z = e^{i\theta}, \quad d\theta = \frac{dz}{iz}, \quad \cos \theta = \frac{1}{2} \left(z + \frac{1}{z} \right). \quad (8)$$

In the z -plane the integration contour is the unit circle $|z| = 1$.

$$\phi(r) = -\frac{2i}{r} \oint_{|z|=1} \frac{dz}{z^2 + 2\frac{d_0}{r}z + 1} \quad (9)$$

The poles of the integrand are given by the roots of the quadratic polynomial in the denominator:

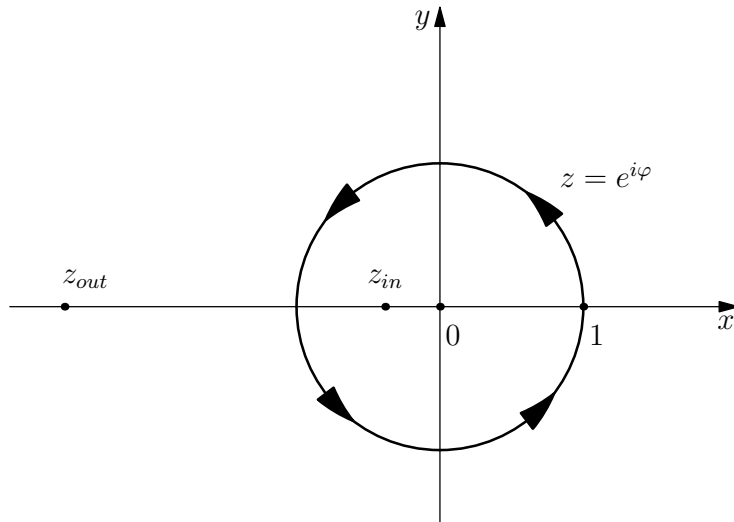
$$z^2 + 2\frac{d_0}{r}z + 1 = 0. \quad (10)$$

$$z_{in,out} = -\frac{d_0}{r} \pm \sqrt{\left(\frac{d_0}{r}\right)^2 - 1}. \quad (11)$$

Since the loop is not crossing the wire, $d_0 > a \geq r$, i.e. $\frac{d_0}{r} > 1$. Therefore both z_{in} and z_{out} are real. Since $z_{in}z_{out} = 1$, only one root, the one with the smaller absolute value, is within the integration contour:

$$z_{in} = -\frac{d_0}{r} + \sqrt{\left(\frac{d_0}{r}\right)^2 - 1}. \quad (12)$$

Figure 2: Integration contour for Eq. (9). The poles of the integrand, z_{in} and z_{out} , are shown for $\frac{d_0}{r} = \frac{3}{2}$.



$$\phi(r) = 2\pi i \left(-\frac{2i}{r} \right) \text{Res} \left(\frac{1}{(z - z_{in})(z - z_{out})}, z = z_{in} \right) \quad (13)$$

$$= \frac{4\pi}{r} \frac{1}{z_{in} - z_{out}} = \frac{2\pi}{r} \frac{1}{\sqrt{\left(\frac{d_0}{r}\right)^2 - 1}} = \frac{2\pi}{\sqrt{d_0^2 - r^2}}. \quad (14)$$

$$\Phi = \frac{\mu_0 I}{2\pi} \int_0^a \phi(r) r \, dr = \mu_0 I \int_0^a \frac{r \, dr}{\sqrt{d_0^2 - r^2}}. \quad (15)$$

Noting that

$$r \, dr = \frac{1}{2} d(r^2) = -\frac{1}{2} d(d_0^2 - r^2) \quad (16)$$

and introducing new integration variable

$$u = d_0^2 - r^2, \quad d_0^2 - a^2 \leq u \leq d_0^2. \quad (17)$$

$$\Phi = \frac{\mu_0 I}{2} \int_{d_0^2 - a^2}^{d_0^2} \frac{du}{\sqrt{u}} = \mu_0 I \sqrt{u} \Big|_{d_0^2 - a^2}^{d_0^2} = \mu_0 I \left(d_0 - \sqrt{d_0^2 - a^2} \right). \quad (18)$$

We can check the result by looking at the limit $a \ll d_0$. We expect the ux to be approximately

$$\Phi \approx \frac{\mu_0 I}{2\pi d_0} \pi a^2 = \frac{\mu_0 I a^2}{2d_0}. \quad (19)$$

Now if we expand the square root in Equation (18), we get

$$\Phi = \mu_0 I d_0 \left(1 - \sqrt{1 - \left(\frac{a}{d_0} \right)^2} \right) \approx \mu_0 I d_0 \left[1 - 1 + \frac{1}{2} \left(\frac{a^2}{d_0^2} \right) \right] = \frac{\mu_0 I a^2}{2d_0} \quad (20)$$

as expected.

Finally, the current in the loop is

$$I = \frac{\varepsilon}{R} = \frac{\mu_0 \dot{I}}{R} \left(d_0 - \sqrt{d_0^2 - a^2} \right), \quad (21)$$

where $\dot{I} = \frac{dI}{dt}$.